

## Commutators and Uncertainty Principle

$$[\hat{A}, \hat{B}] = 0 = [\hat{A}\hat{B} - \hat{B}\hat{A}]$$

Y

2 operators commute

$$\Rightarrow [\hat{T}_n, \hat{P}_n] \Rightarrow (\hat{T}_n \hat{P}_n - \hat{P}_n \hat{T}_n) f(x)$$

commute

$$\hat{T}_n \hat{P}_n f(x) = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} - i\hbar \frac{d}{dx} f$$

equal

$$= \frac{i\hbar^3}{2m} \frac{d^3 f}{dx^3}$$

$$\hat{P}_n \hat{T}_n f(x) = -i\hbar \frac{d}{dx} - \frac{\hbar^2}{2m} \frac{d^2}{dx^2} f$$

$$= \frac{i\hbar^3}{2m} \frac{d^3 f}{dx^3}$$

$$[\hat{x}, \hat{P}_n] \Rightarrow [\hat{x} \hat{P}_n - \hat{P}_n \hat{x}] f(x)$$

$$\hat{x} \hat{P}_n f(x) = x - i\hbar \frac{d}{dx} f = -i\hbar x \frac{df}{dx}$$

$$\hat{P}_n \hat{x} f(x) = -i\hbar \frac{d}{dx} [x f(x)]$$

$$= -i\hbar f(x) - i\hbar x \frac{df}{dx}$$

$$[\hat{x}, p_x] = i\hbar$$

Variance:

$$\sigma_A^2 = \langle (A - \langle A \rangle)^2 \rangle$$



$$\int \Psi^* (\hat{A} - \langle A \rangle)^2 \Psi dx$$

$$= \int \Psi^* (\hat{A}^2 - 2\hat{A}\langle A \rangle + \langle A \rangle^2) \Psi dx$$

$$= \int \Psi^* \hat{A}^2 \Psi dx - 2 \int \Psi^* \hat{A} \langle A \rangle \Psi dx + \int \Psi^* \langle A \rangle^2 \Psi dx$$

$$= \langle A^2 \rangle - 2\langle A \rangle \langle A \rangle + \langle A \rangle^2$$

$$\sigma_A^2 = \langle A^2 \rangle - \langle A \rangle^2$$

$$\sigma_A \sigma_B \geq \frac{1}{2} \left| \int \Psi^* [\hat{A}, \hat{B}] \Psi dx \right|$$

$$\sigma_A \sigma_B \geq \frac{1}{2} \left| \langle [\hat{A}, \hat{B}] \rangle \right|$$

## Particle in a box (1-1)

$$\Delta x \Delta p_x \quad \text{or} \quad \sigma_x \sigma_{p_x}$$

$$\Delta x \quad \text{or} \quad \sigma_x = \sqrt{\langle x^2 \rangle - \langle x \rangle^2}$$

$$\Delta p_x \quad \text{or} \quad \sigma_{p_x} = \sqrt{\langle p_x^2 \rangle - \langle p_x \rangle^2}$$

$$\sigma_x = \sqrt{\left( \frac{L^2}{3} - \frac{L^2}{2n^2\pi^2} \right) - \left( \frac{L}{2} \right)^2}$$

$$= \sqrt{\frac{L^2}{12} - \frac{L^2}{2n^2\pi^2}}$$

$$= \sqrt{\frac{L^2}{4n^2\pi^2} \left[ \frac{n^2\pi^2}{3} - 2 \right]}$$

$$\sigma_x = \frac{L}{2n\pi} \sqrt{\left( \frac{n^2\pi^2}{3} - 2 \right)}$$

$$\sigma_{p_x} = \sqrt{\langle p_x^2 \rangle - \langle p_x \rangle^2}$$

$\hookrightarrow 0$

$$= \sqrt{2m\langle E \rangle} = \sqrt{2m \frac{n^2 h^2}{8mL^2}}$$

$$\sigma_{p_x} = \sqrt{\frac{n^2 h^2}{4L^2}} = \frac{nh}{2L}$$

$$\sigma_x \sigma_{p_x} = \frac{n\hbar}{2L} \frac{L}{2n\pi} \sqrt{\left(\frac{n^2\pi^2}{3} - 2\right)}$$

$$= \frac{\hbar}{4\pi} \sqrt{\left(\frac{n^2\pi^2}{3} - 2\right)}$$

n=1

$$\sigma_x \sigma_{p_x} = 0.568 \hbar$$

$$\sigma_x \sigma_{p_x} > \frac{\hbar}{2}$$

$$\sigma_A \sigma_B \geq \frac{1}{2} | \langle [\hat{A}, \hat{B}] \rangle |$$

$$\hat{A} = x; \quad \hat{B} = p_x$$

$$\langle [\hat{A}, \hat{B}] \rangle = \int \psi^* [\hat{x}, \hat{p}_x] \psi dx$$

$$= \int \psi^* [\hat{x}\hat{p}_x - \hat{p}_x\hat{x}] \psi dx$$

$$= i\hbar \int \psi^* \psi dx$$

$$= i\hbar$$

$$\sigma_A \sigma_B \geq \frac{1}{2} |i\hbar|$$

$$\sigma_x \sigma_{p_x} \geq \frac{\hbar}{2}$$

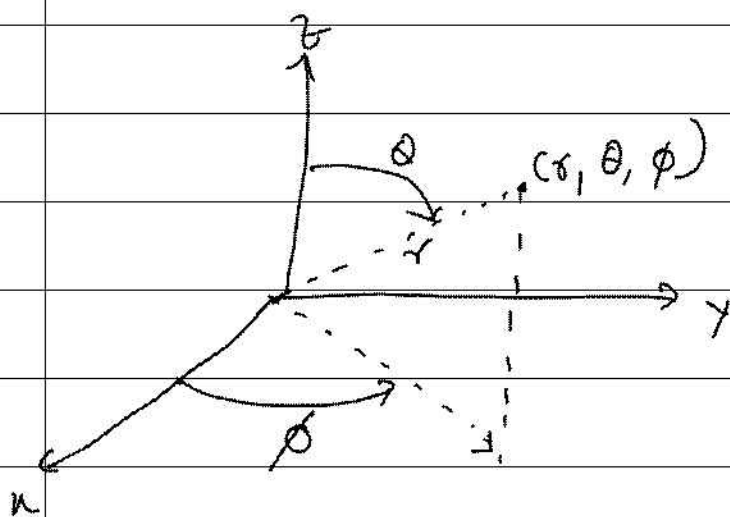
~~~~~

# Rotational Motion

$$0 < r < \infty$$

$$0 < \theta < \pi$$

$$0 < \phi < 2\pi$$



$$x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

spherical polar

coordinates

$$\hat{H} = -\frac{\hbar^2}{2m} \underbrace{\left[ \frac{\partial^2}{\partial r^2} + \frac{\partial^2}{\partial r^2} + \frac{\partial^2}{\partial z^2} \right]}_{\nabla^2}$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$$

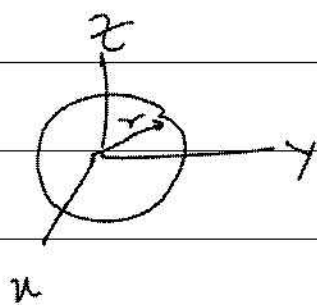
$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \Lambda^2 \quad \text{--- (1)}$$

$$\Lambda^2 = \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2}$$

↑

Legendrian

# Particle on a ring



$r$  is fixed